



Introduction to Computer Graphics

5. Clipping

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Textbook: E. Angel, Interactive Computer Graphics, 5th Ed., Addison Wesley

Ref: Hearn and Baker, Computer Graphics, 3rd Ed., Prentice Hall

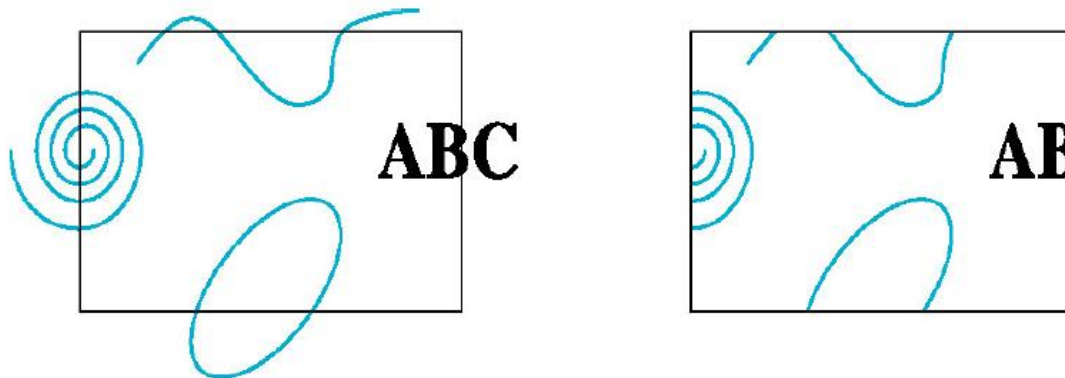


Objectives

- Introduce basic implementation strategies
- 2D Clipping
 - Lines
 - Polygons
- Clipping in 3D

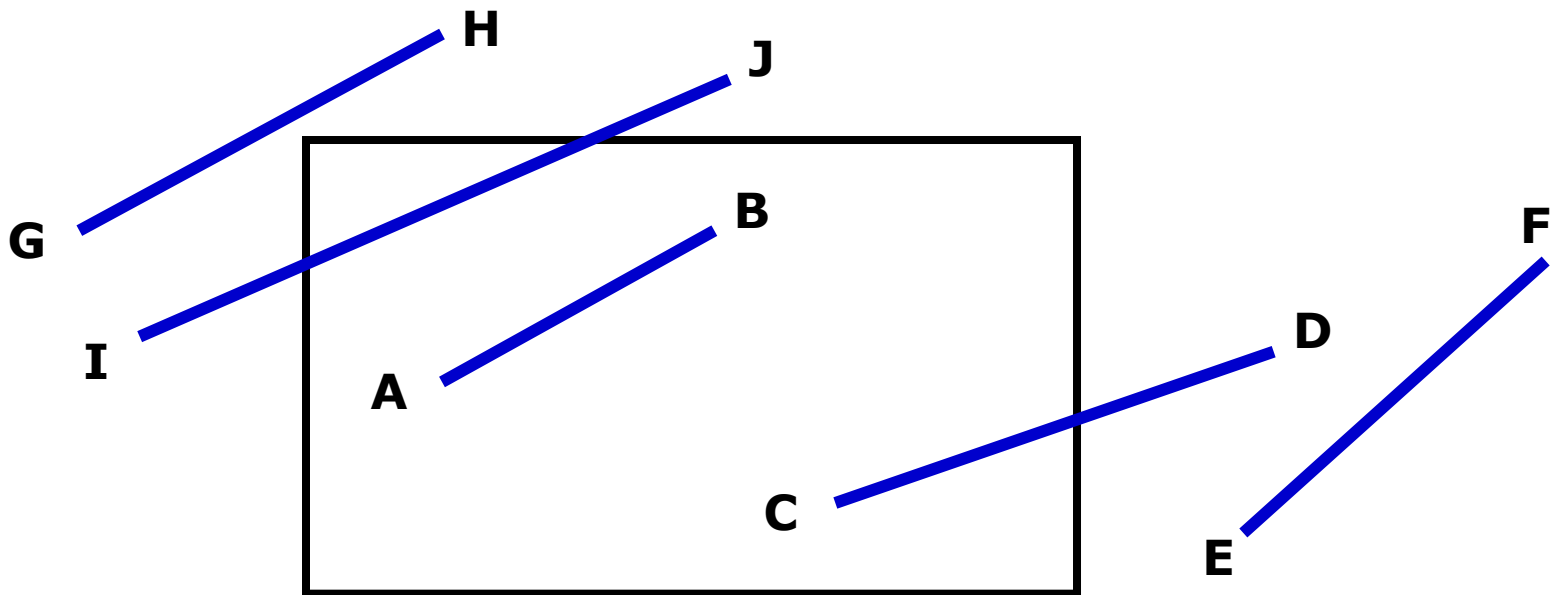
Clipping

- 2D against clipping window
- 3D against clipping volume
- Easy for line segments polygons
- Hard for curves and text
 - Convert to lines or polygons first



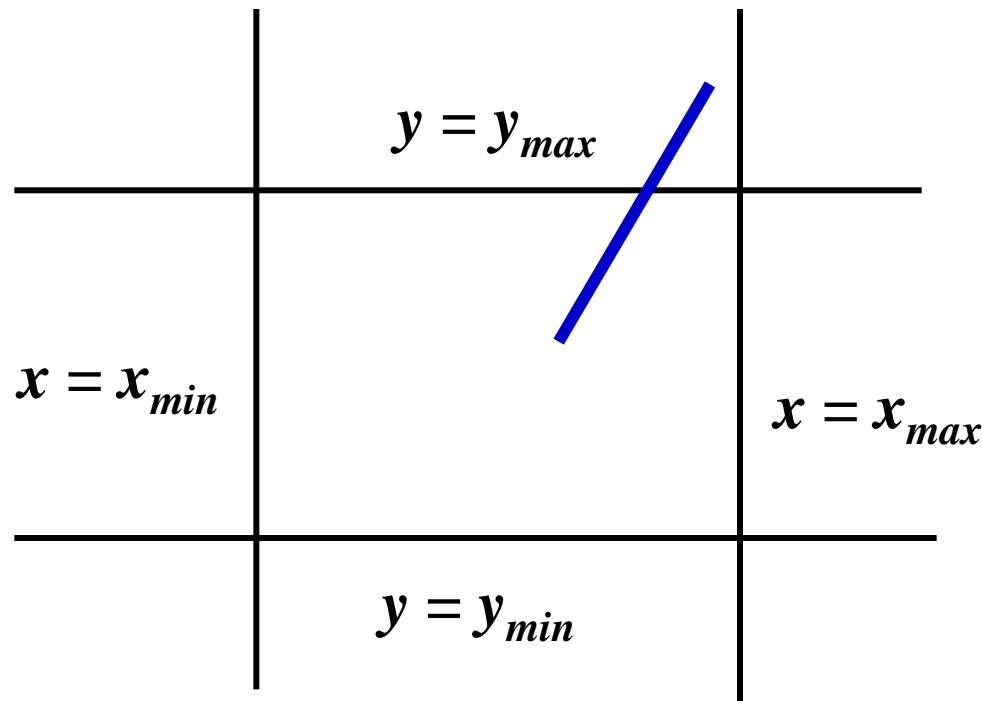
Clipping 2D Line Segments

- Brute force approach: compute intersections with all sides of clipping window
 - Inefficient: one division per intersection



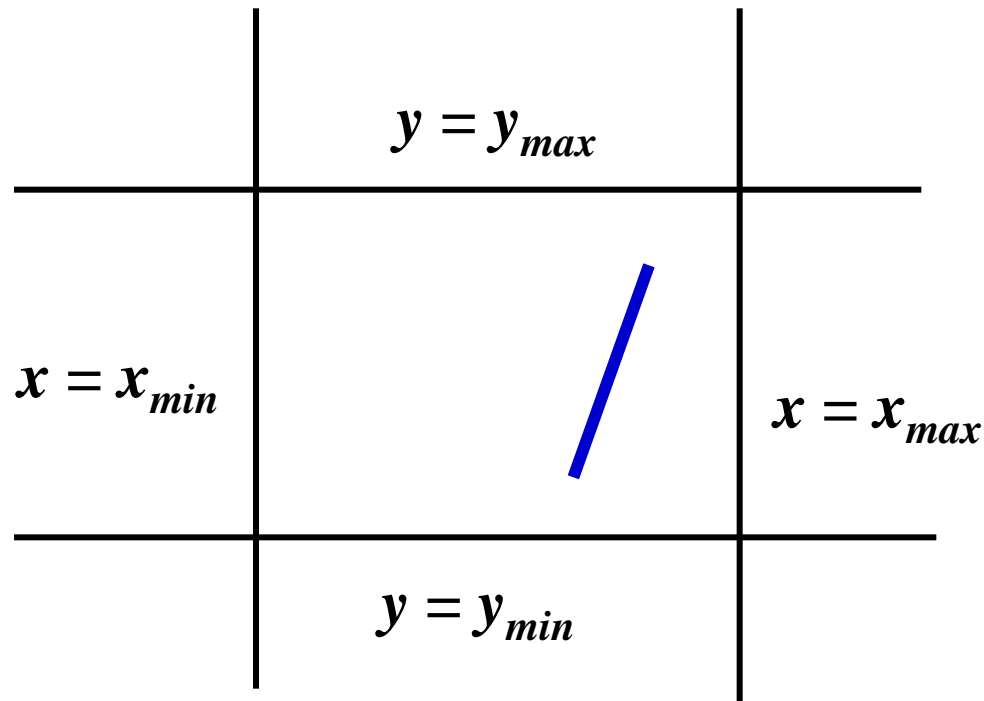
Cohen-Sutherland Algorithm

- Idea: eliminate as many cases as possible without computing intersections
- Start with four lines that determine the sides of the clipping window



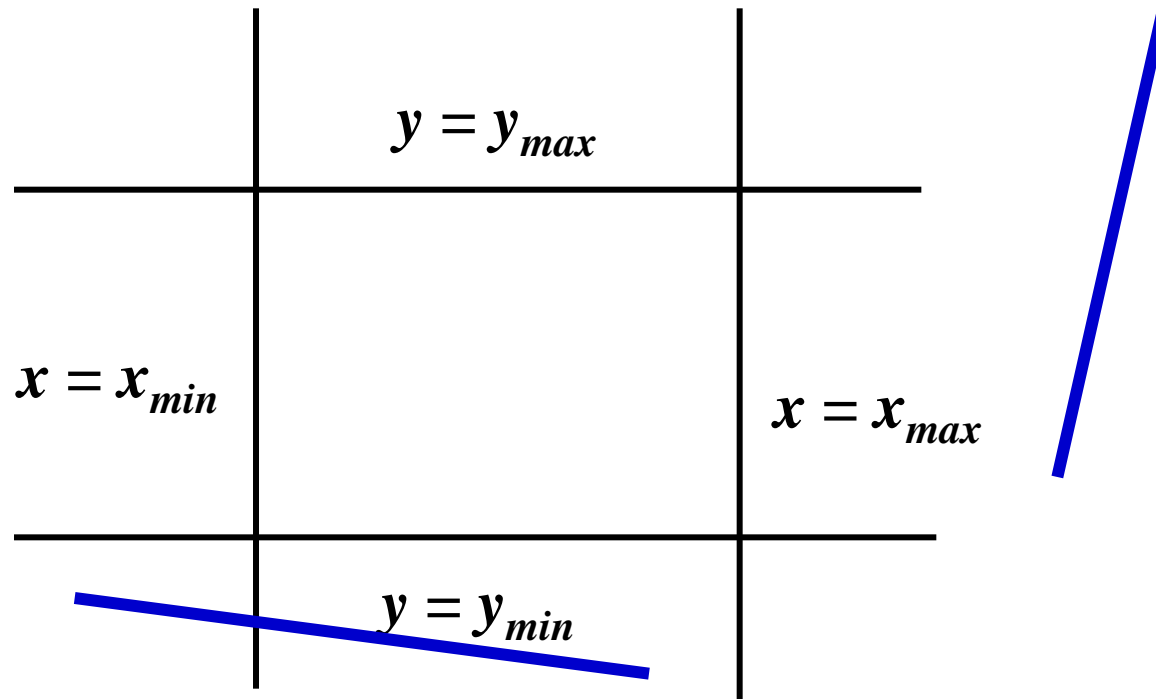
Case 1

- Case 1: both endpoints of line segment inside all four lines
 - Draw (accept) line segment as is



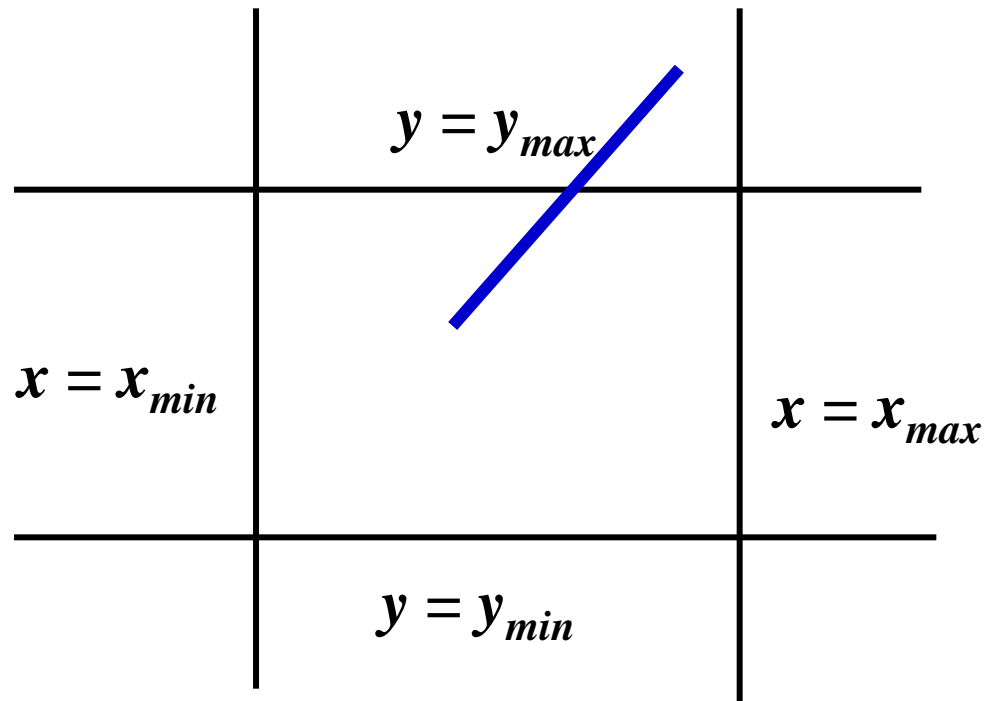
Case 2

- Case 2: both endpoints outside all lines and on same side of a line
 - Discard (reject) the line segment



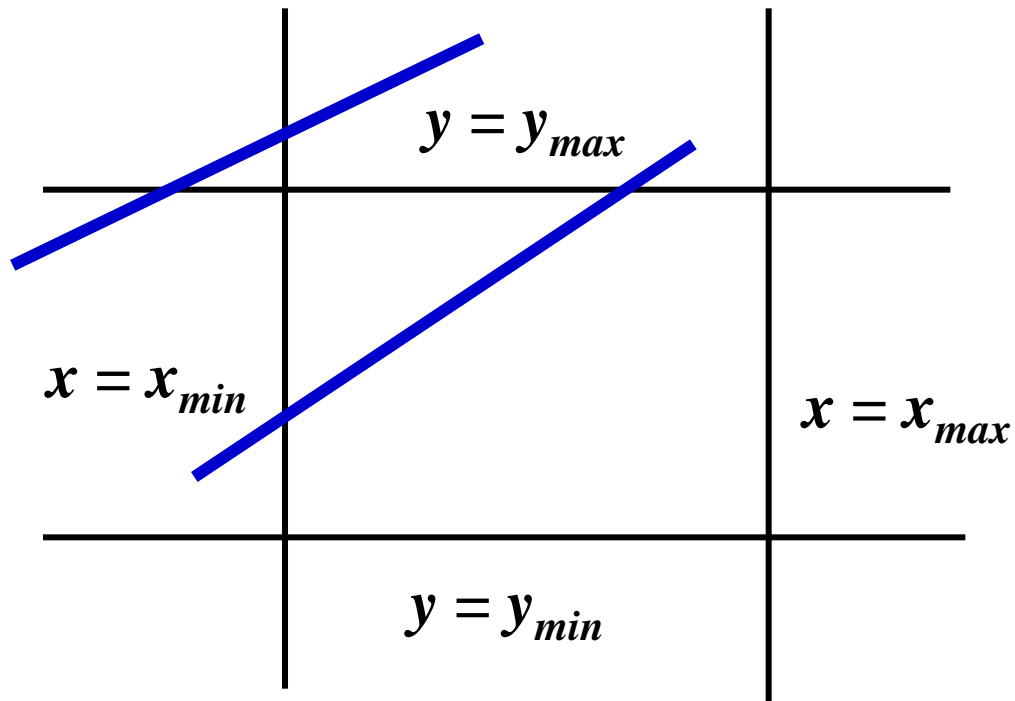
Case 3

- One endpoint inside, one outside
 - Must do at least one intersection



Case 4

- Both outside
 - May have part inside
 - Must do at least one intersection



Defining Outcodes

- For each endpoint, define an outcode
 - [b0 b1 b2 b3]
- Outcodes divide space into 9 regions
- Computation of outcode requires at most 4 subtractions

| | | |
|------|------|------|
| 1001 | 1000 | 1010 |
| 0001 | 0000 | 0010 |
| 0101 | 0100 | 0110 |

b0 = 1 if $y > y_{\max}$, 0 otherwise

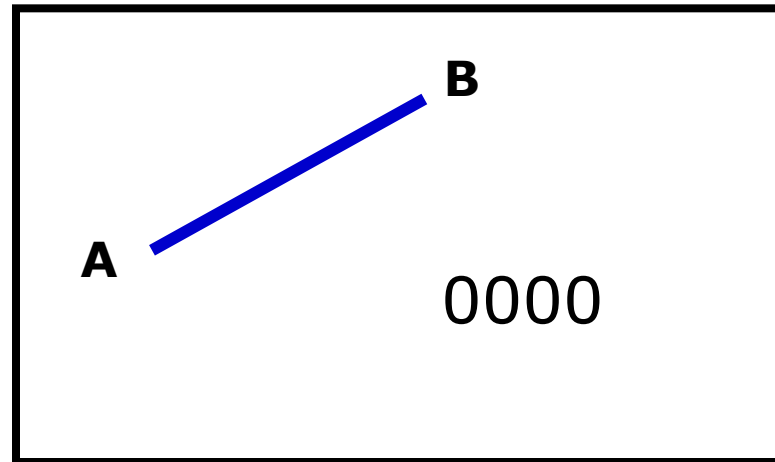
b1 = 1 if $y < y_{\min}$, 0 otherwise

b2 = 1 if $x > x_{\max}$, 0 otherwise

b3 = 1 if $x < x_{\min}$, 0 otherwise

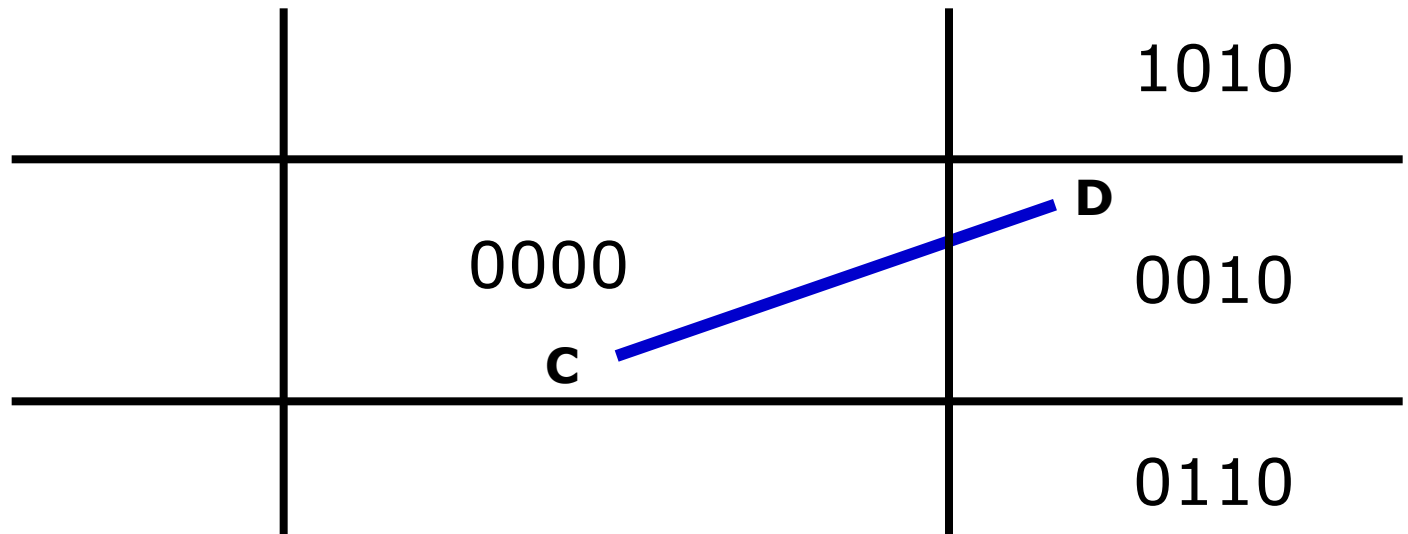
Using Outcodes

- AB: $\text{outcode}(A) = \text{outcode}(B) = 0$
 - Accept line segment



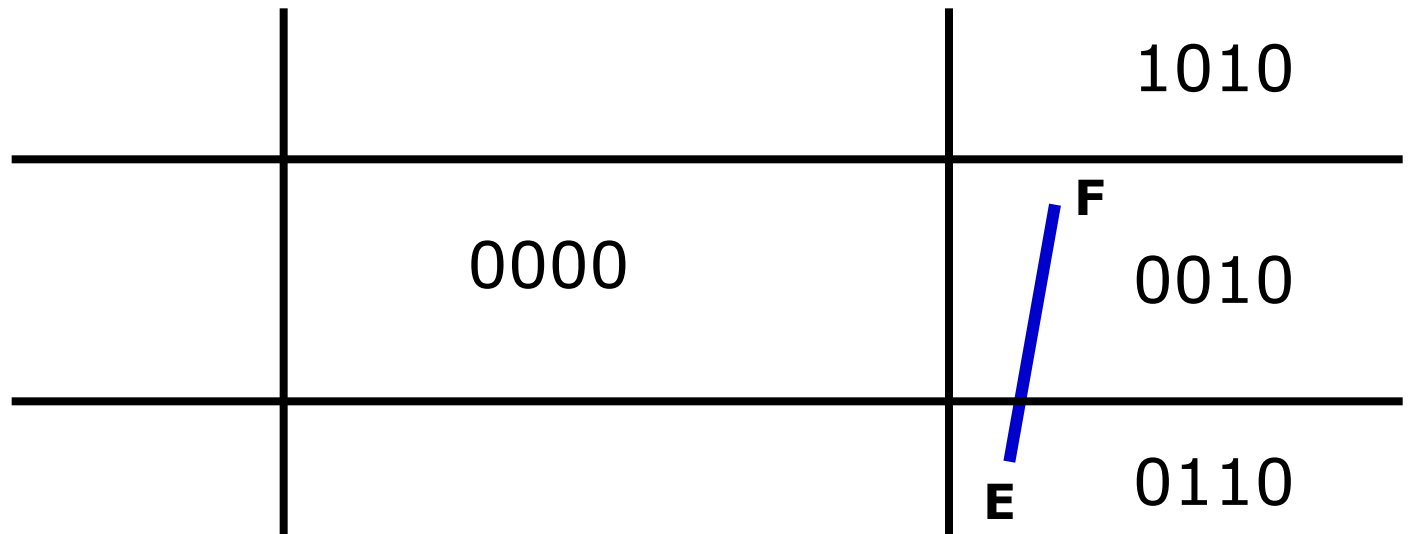
Using Outcodes

- CD: outcode (C) = 0, outcode(D) \neq 0
 - Compute intersection
 - Location of 1 in outcode(D) determines which edge to intersect with
 - Note if there were a segment from C to a point in a region with 2 ones in outcode, we might have to do two intersections



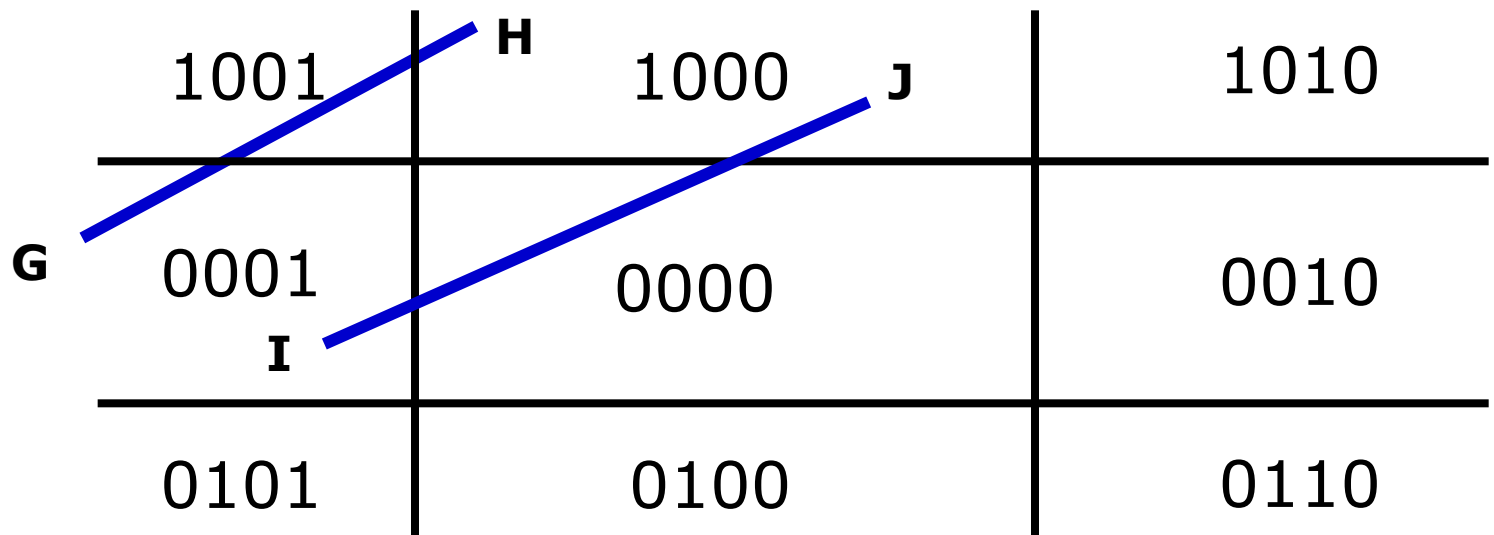
Using Outcodes

- EF: outcode(E) logically ANDed with outcode(F) (bitwise) $\neq 0$
 - Both outcodes have a 1 bit in the same place
 - Line segment is outside of corresponding side of clipping window
 - reject



Using Outcodes

- GH and IJ: same outcodes, neither zero but logical AND yields zero
 - Shorten line segment by intersecting with one of sides of window
 - Compute outcode of intersection (new endpoint of shortened line segment)
 - Reexecute algorithm



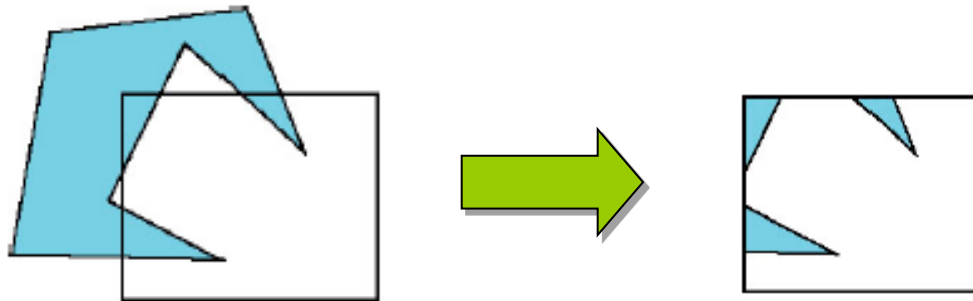


Efficiency

- In many applications, the clipping window is small relative to the size of the entire data base
 - Most line segments can be eliminated based on their outcodes.

Polygon Clipping

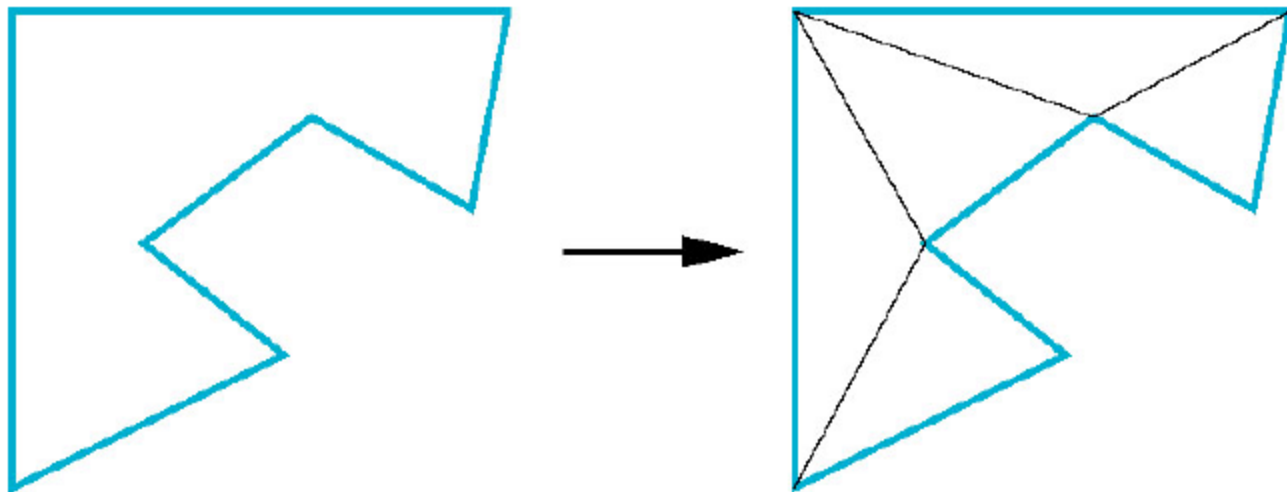
- Not as simple as line segment clipping
 - Clipping a line segment yields at most one line segment
 - Clipping a polygon can yield multiple polygons



- However, clipping a convex polygon can yield at most one other polygon

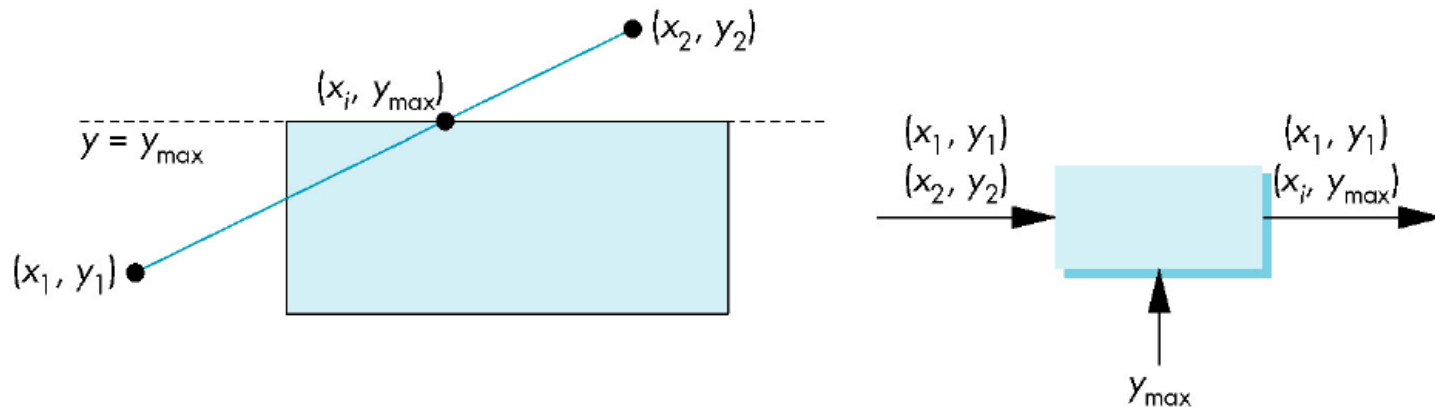
Tessellation and Convexity

- One strategy is to replace nonconvex (concave) polygons with a set of triangular polygons (a tessellation)
- Also makes fill easier



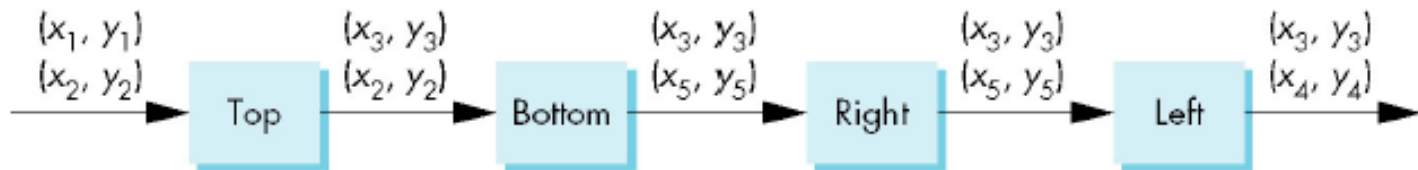
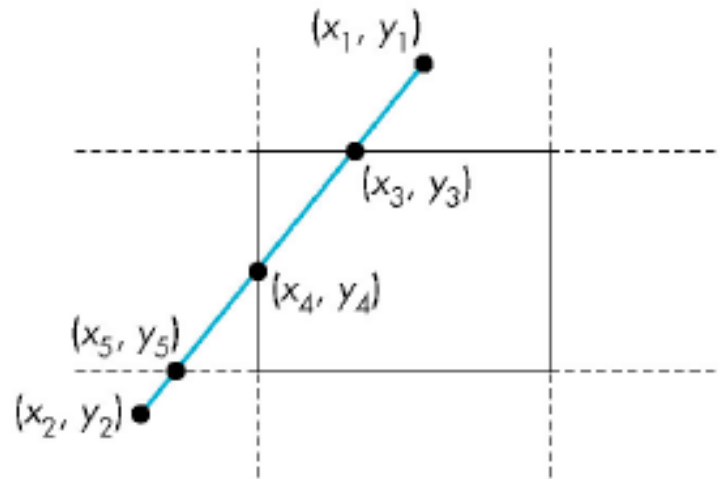
Clipping as a Black Box

- Consider line segment clipping as a process that takes in two vertices and produces either no vertices or the vertices of a clipped line segment.



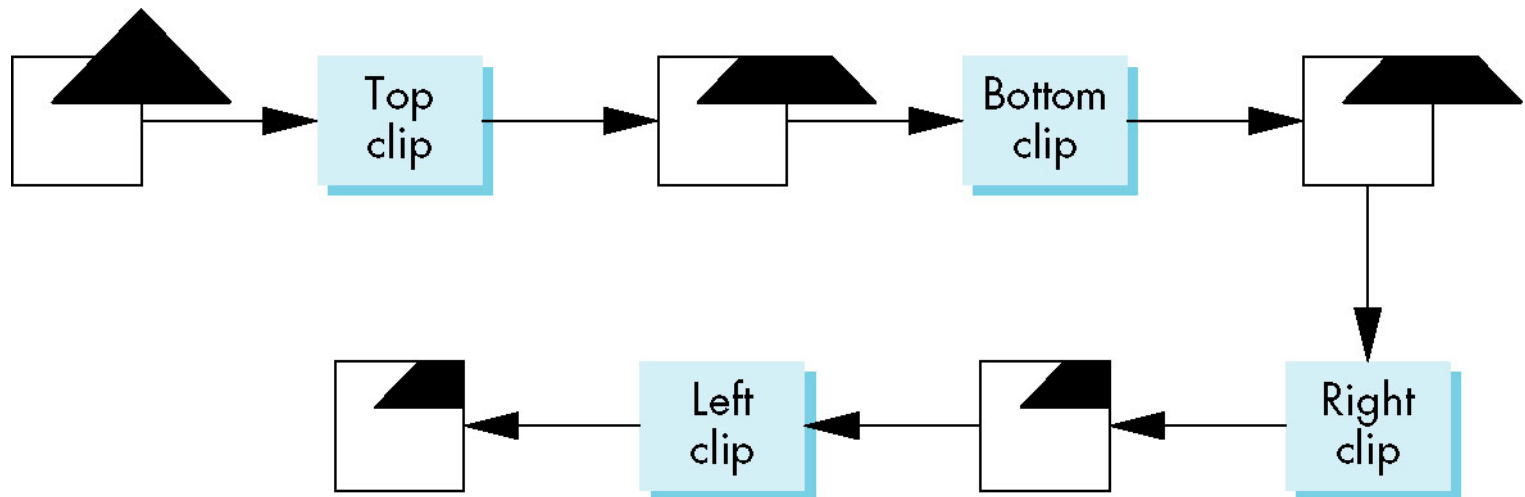
Pipeline Clipping of Line Segments

- Clipping against each side of window is independent of other sides
 - Can use four independent clippers in a pipeline



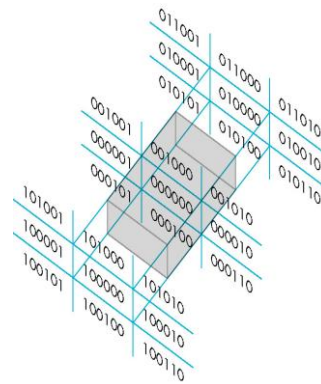
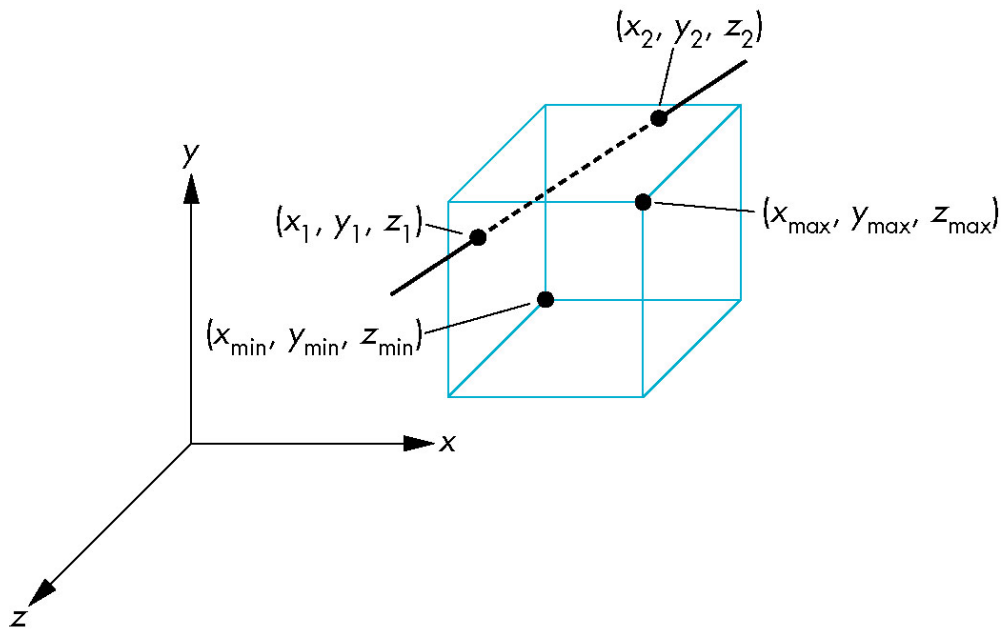
Pipeline Clipping of Polygons

- Sutherland-Hodgman algorithm
- Strategy used in SGI Geometry Engine
- Small increase in latency



Cohen-Sutherland Method in 3D

- Use 6-bit outcodes
 - When needed, clip line segment against planes



Cohen-Sutherland Method in 3D

Check for outcodes:

$$-1 \leq x_p \leq 1, \quad -1 \leq y_p \leq 1, \quad -1 \leq z_p \leq 1$$

Since

$$\begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \xRightarrow{\text{SRT...}} \dots \Rightarrow \begin{bmatrix} x_h \\ y_h \\ z_h \\ h \end{bmatrix} \xRightarrow{\text{Divide } h} \dots \Rightarrow \begin{bmatrix} x_h/h \\ y_h/h \\ z_h/h \\ 1 \end{bmatrix} = \begin{bmatrix} x_p \\ y_p \\ z_p \\ 1 \end{bmatrix}$$

To avoid unnecessary float division, We can check

$$-h \leq x_h \leq h, \quad -h \leq y_h \leq h, \quad -h \leq z_h \leq h$$

Cohen-Sutherland Method in 3D

- If $\text{outcode}(A) == \text{outcode}(B) == 0$
 - Accept the whole line segment.
- If $(\text{outcode}(A) \text{ and } \text{outcode}(B)) \neq 0$
 - Reject the line segment.
- Other cases
 - Calculate an intersection (according to outcode bits)
 - Then check outcode again
- Note: use parametric forms

$$x_h = x_{ha} + (x_{hb} - x_{ha})u$$

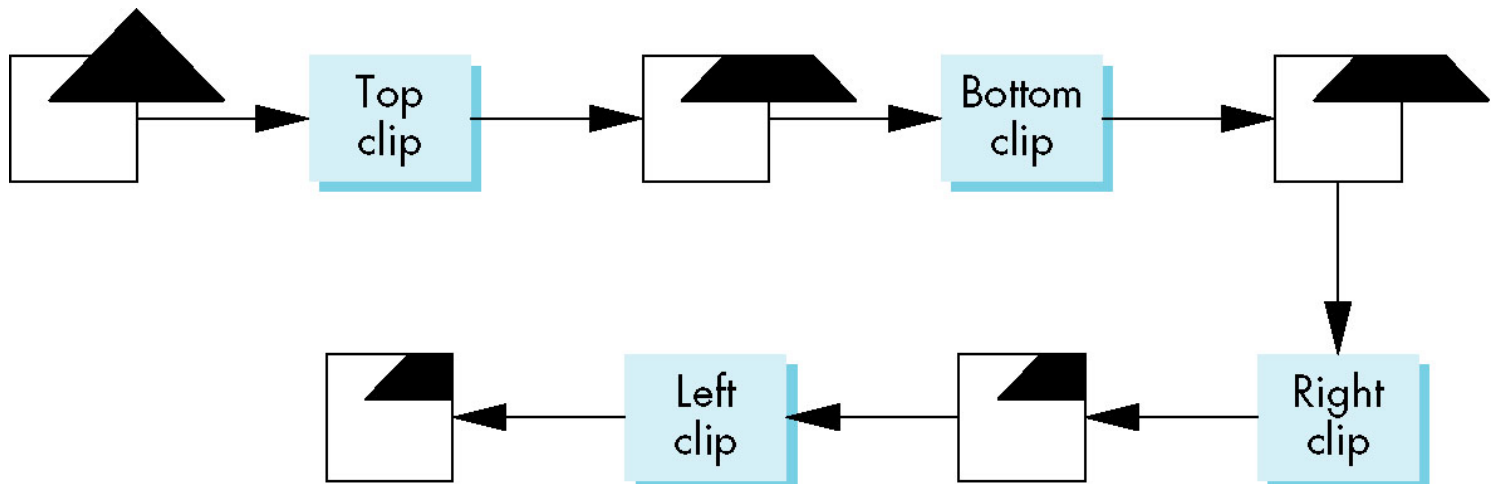
$$y_h = y_{ha} + (y_{hb} - y_{ha})u$$

$$z_h = z_{ha} + (z_{hb} - z_{ha})u$$

$$h = h_a + (h_b - h_a)u$$

Polygon Clipping in 3D

- Similar to 2D clipping
 - Bounding box
 - Clipping with each clipping plane
 - Etc.....



Bounding Boxes

- Rather than doing clipping on a complex polygon, we can use an axis-aligned bounding box or extent
 - Smallest rectangle aligned with axes that encloses the polygon
 - Simple to compute: max and min of x and y

